

ELMAR – The versatile platform for real-time applications

Cut the number of elctronic control units with ELMAR. The ELMAR framework is a real-time architecture for AMD® Zynq® UltraScale+TM MPSoCs that enables the operation of low latency regulating algorithms (optionally on the basis of Simulink®) parallel to embedded Linux distribution. A lightweight hypervisor ensures a distinct separation between Linux management and control on the basis of an RTOS. Linux offers a web server, parameter administration, a firmware update mechanism and further features that simplify field administration of the board. In-house developed inter-core communication (ICC) provides synchronized communication between the ARM® cores for real-time applications.



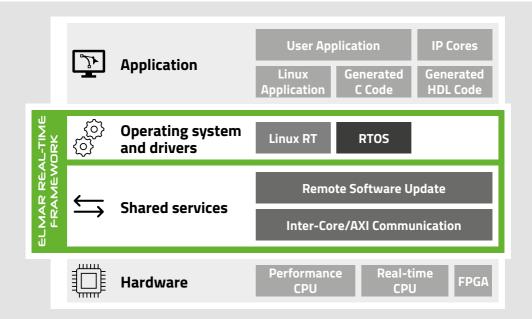
Top features

Powerful, embedded control platform

Flexible framework for control applications

Designed for lowest latencies and hard real-time conditions

Architecture





Overview of specific features



INTER-CORE COMMUNICATION
MECHANISMUS



VIRTUAL NETWORK AND PRIORITIZATION



PARAMETER MANAGER



HW AND SW WATCHDOG



CENTRALIZED LOGGING AND EVENT LOGGING



REMOTE SOFTWARE UPDATE



SECURE BOOT



IoT SUPPORT



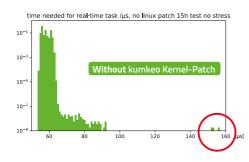
SIMULINK®TARGET

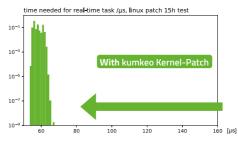


SCALABLE

Performance

By applying our kernel patch, which has been specially developed for this platform, we can guarantee a stable 10 kHz frequency on the real-time cores. This is measured using a complex industrial Simulink® control algorithm.





Benefits



TURNKEY FRAME-WORK FOR INTEGRATING AN APPLICATION



COMBINES THE BENEFITS OF BOTH ENVIRONMENTS (LINUX AND RTOS)



PREQUALIFIED AND DEPLOYABLE EVALUATION BOARD



FRAMEWORK
MAINTENANCE
CARRIED OUT
BY kumkeo



FOCUS ON CORE COMPETENCIES





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